Massively Parallel Graph Algorithms

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Research environment

Places (and people)

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• University of Wrocław (with Tomasz Jurdziński)

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- University of Wrocław (with Tomasz Jurdziński)
- ETH Zurich (with Mohsen Ghaffari)

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Financial support

- NCN grant no 2017/25/B/ST6/02010 (Tomasz' OPUS13 grant)
- NCN grant no 2019/32/T/ST6/00566 (my ETIUDA7 grant)
- FNP START scholarship (year 2020)

Models of computation

Computational model

- industry: MapReduce, Spark, ...
- TCS community: Massively Parallel Computation (MPC) model

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Initial take on MapReduce

input data

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• Easy: aggregative functions, e.g. sum, min, max, ...

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There are 2 kinds of problems:

- Easy: aggregative functions, e.g. sum, min, max, ...
- Non trivial: some graph problems, e.g. Minimum Spanning Tree

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MPC model

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Computing in multiple rounds

synchronous rounds

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Computing in multiple rounds

- synchronous rounds
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Computing in multiple rounds

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MPC model

Parameters

• each machine gets input of size S / has communication limit S

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MPC model

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- $\cdot\,$ each machine gets input of size S / has communication limit S
- for input of size *N*, the number of machines is $\mathcal{O}(\frac{N}{5})$

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Remark: m = # of edges, n = # of vertices, $\delta = \min$ degree

Congested Clique Model
• multi party communication



- multi party communication
- *n* players with IDs in [*n*]



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Graph problems in the Congested Clique

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Graph problems in the Congested Clique

- \cdot each player represents single node of the input graph
- input: each player knows set of incident edges
- $\cdot\,$ result: each player knows (part of) the output



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Almost equivalent to MPC with $\mathcal{O}(n)$ local memory.



Output of the community (recent FOCS / STOC / SODA)

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*Dynamic Graph Algorithms with Batch Updates in the Massively Parallel Computation Model.(N., Onak; SODA'21)

*Walking Randomly, Massively, and Efficiently.(Łącki, Mitrović, Onak, Sankowski; STOC'20)

*Faster Algorithms for Edge Connectivity via Random 2-Out Contractions. (Ghaffari, N. Thorup, SODA'20)

*Parallel Batch-Dynamic Graphs: Constant Round Algorithms and Lower Bounds. (Durfee, Dhulipala, Kulkarni, Peng, Sawlani, Sun, SODA'20) *Exponentially Faster Massively Parallel Maximal Matching. (Behnezhad,

Hajiaghayi, Harris; FOCS'19)

*Conditional Hardness Results for Massively Parallel Computation from Distributed Lower Bounds. (Ghaffari, Kuhn, Uitto; FOCS'19)

*Near-Optimal Massively Parallel Graph Connectivity. (Behnezhad,

Dhulipala, Esfandiari, Łącki, Mirrokni; FOCS'19)

*Massively parallel approximation algorithms for edit distance and longest common subsequence(Hajiaghayi , Seddighin, Sun, SODA'19)

*Sparsifying Distributed Algorithms with Ramifications in Massively Parallel Computation and Centralized Local Computation.(Ghaffari, Uitto; SODA'19)

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*Parallel Graph Connectivity in Log Diameter Rounds.(Andoni, Song, Stein, Wang, Zhong; FOCS'18)

- *Round compression for parallel matching algorithms.(Czumaj, Łącki, Mądry, Mitrović, Onak, Sankowski; STOC'18)
- *MST in O(1) Rounds of Congested Clique.(Jurdzinski, N.; SODA'18)
- *Efficient massively parallel methods for dynamic programming.(Im,

Moseley, Sun; STOC'17)

- ***A New Framework for Distributed Submodular Maximization.**(Barbosa, Ene, Nguyên, Ward; FOCS'16)
- *Randomized Composable Core-sets for Distributed Submodular Maximization. (Mirrokni, Zadimoghaddam; STOC'15)
- *Parallel Algorithms for Geometric Graph Problems.(Andoni, Nikolov, Onak, Yaroslavtsev, STOC'14)
- ***A Model of Computation for MapReduce.** (Karloff, Suri, Vassilvitskii, SODA'10)

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Including other papers makes the list significantly longer.

My research

1. Minimum Spanning Tree problem

Minimum Spanning Tree problem
Minimum Cut problem

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- 2. Minimum Cut problem
- 3. Dynamic Graph algorithms

My research

Minimum Spanning Tree problem

year	round	det.?	authors; source
	complexity		

MST -- a problem with a long history of results

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1926	$\mathcal{O}(\log n)$	yes	Boruvka; Práce Mor. Přírodověd. Spol. V Brně

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		110	Sardeshmukh, Scquizzato; PODC'16

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2018	$\mathcal{O}(1)$	no	Jurdziński, N.; SODA'18
2019	<i>O</i> (1)	yes	N.; arxiv preprint

Instance of MST problem \rightarrow several instances of Connected Components problem.

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Spanning Forest algorithm

- 1. Select $\mathcal{O}(n)$ edges (in a certain way).
- 2. Compute connected components on selected edges.
- 3. Partition the component graph into edge disjoint subgraphs, constructed in a certain way.
- 4. Sparsify all subgraphs, in parallel.

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 \Rightarrow v in component of size at least deg(v) + 1.,

Spanning Forest algorithm

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s.t. $\sum_i \sqrt{|V_i| \cdot |E_i|} = \mathcal{O}(n).$

My research

Minimum Cut problem

2-out contraction - algorithm for simple graphs



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2-out contraction - algorithm for simple graphs

- 1. For each vertex mark 2 random incident edges.
- 2. Contract connected components spanned by marked edges.



2-out contraction - properties (for simple graphs)



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Improved Algorithms:

1. Congested Clique / MPC: $\mathcal{O}(1)$ round algorithm.

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MPC algorithms for weighted graphs (Ghaffari, N.; PODC'20)

Linear local memory

Adaptation of algorithm based on tree packings (Karger, STOC'96).

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Sublinear local memory

 $(2 + \varepsilon)$ -approximation in $\mathcal{O}(\log n \log \log n)$ rounds, modification of contraction based algorithm for PRAM (Karger, SODA'94).

My research

Dynamic Graph algorithms

Motivation

In practice:
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- solving problem repeatedly
- \cdot slightly changing data set

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More formally

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In practice:

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More formally

- G_1, G_2, \ldots, G_i is G_{i-1} with up to k modifications.
- Goal: compute S_1, S_2, \ldots , a sequence of solutions.

There is no proven separation between linear memory MPC and sublinear memory MPC. However, we know substantially better algorithms for $\mathcal{O}(n)$ memory regime.

	$S \in \mathcal{O}(n)$	$S \in \mathcal{O}(n^{1-\varepsilon})$
MST	<i>O</i> (1)	$\mathcal{O}(\log n)$
2-EC	<i>O</i> (1)	$\mathcal{O}(\log n)$
MIS	$\mathcal{O}(\log \log n)$	$\tilde{\mathcal{O}}(\sqrt{\log n})$
MM	$\mathcal{O}(\log \log n)$	$\tilde{\mathcal{O}}(\sqrt{\log n})$

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2-cycle Conjecture

Any algorithm that distinguish between single-cycle input and two-cycle input, with $\mathcal{O}(n^{1-\varepsilon})$ local memory, and $\operatorname{poly}(n)$ global memory requires $\Omega(\log n)$ rounds.

In practice:

- solving problem repeatedly
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More formally

- G_1, G_2, \ldots, G_i is G_{i-1} with up to k modifications.
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In practice:

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Our results (for $k \in \mathcal{O}(S)$)

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Better-than-static algorithms for $k \in \Theta(S^{1+\varepsilon'})$? Unlikely.

Thanks!

Thanks!

For the details:

- email me: knowicki@cs.uni.wroc.pl
- ask me in person